



state_interfaces
joint1/position
joint1/velocity
joint2/position
joint2/velocity
joint3/position
joint3/velocity
joint4/position
joint4/velocity
joint5/position
joint5/velocity
joint6/position
joint6/velocity

controller	
joint1/position	joint1/position
joint1/velocity	joint1/velocity
joint2/position	joint2/position
joint2/velocity	joint2/velocity
joint3/position	joint3/position
joint3/velocity	joint3/velocity
joint4/position	joint4/position
joint4/velocity	joint4/velocity
joint5/position	joint5/position
joint5/velocity	joint5/velocity
joint6/position	joint6/position
joint6/velocity	joint6/velocity

chained_controller	
joint1/position	joint1/position
joint2/position	joint1/velocity
joint3/position	joint1/velocity
joint4/position	joint2/position
joint5/position	joint2/velocity
joint6/position	joint3/position
joint1/velocity	joint3/velocity
joint2/velocity	joint4/position
joint3/velocity	joint4/velocity
joint4/velocity	joint5/position
joint5/velocity	joint5/velocity
joint6/position	joint5/position
joint6/velocity	joint6/velocity

command_interfaces
joint1/position
joint1/velocity
joint2/position
joint2/velocity
joint3/position
joint3/velocity
joint4/position
joint4/velocity
joint5/position
joint5/velocity
joint6/position
joint6/velocity