

The Compact Muon Solenoid Experiment

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The L1 Track Trigger Upgrade: Properties, Efficiencies, and Rates for Track Stubs

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Abstract

A new CMS tracker detector will be installed for the High Luminosity LHC. The new tracker will read out hits at a sufficiently high rate to allow track reconstruction in real time. This will allow the inclusion of tracking information in the Level 1 (L1) trigger system for the first time, dramatically lowering the CMS L1 trigger rate. Stubs are building blocks of the L1 trigger system. Therefore, determination and measurement of the stub properties are crucial tasks. In this note, we study various features of stubs for the CMS experiment phase II track trigger upgrade including stub rates, stub construction efficiency, stub transmission efficiency, stub bend decoding, etc. Consequently, new stub window tunes are proposed which have high stub construction efficiencies with the lowest possible rates. Additionally we present a new method of stub bend decoding which can cope with changing stub window sizes. This work is based on a full simulation of LHC events with high pileup.

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1. Introduction

1 Introduction

- ² The goal of the High-Luminosity LHC program is to collect an integrated luminosity of 3000 fb⁻¹
- in about ten years of operations starting in 2028 and with a peak luminosity of 7.5×10^{34} cm⁻²s⁻¹.
- ⁴ As the bunch crossing separation will stay the same as today (25 ns), the increase of instanta-
- ⁵ neous luminosity will result in up to 200 inelastic proton-proton collisions per bunch crossing
- ⁶ (pileup). The CMS detector needs to be substantially upgraded in order to exploit the increase
- 7 in luminosity provided by the HL-LHC [1].
- 8 A major new functionality of the CMS detector for the HL-LHC is the inclusion of data from the
- 9 Outer Tracker (OT) in the L1 trigger, facilitated by the readout of silicon tracking information at
- an unprecedented 40 MHz data rate [2]. The primary function that enables this improvement is
- the ability to perform local transverse momentum ($p_{\rm T}$) measurements with the detector front-
- end electronics. Studies have shown that 97% (99%) of the particles created in pp interactions at 14 TeV have $p_T < 2$ GeV ($p_T < 3$ GeV). The readout rate of soft interactions can be reduced
- ¹⁴ by a factor of 10 via selections on the local $p_{\rm T}$ measurements [2].
- ¹⁵ New tracking modules utilize a pair of closely spaced silicon sensors (1.6 4.0 mm) and on-
- ¹⁶ detector correlation logic in order to discriminate charged particle tracks with a $p_{\rm T}$ exceeding a
- ¹⁷ threshold of 2-3 GeV. Two module types are foreseen for the OT:
- PS modules: A PS module is composed of one strip sensor (two rows of 960 AC-coupled strips with dimensions 2.35 cm×100 μm) and a one macro-pixel sensor (30 720 DC-coupled pixels with dimensions 1.5 mm×100 μm).
- 2S modules: A 2S module is composed of two strip sensors (two rows of 1016 AC-coupled strips with dimensions 5 cm×90 µm per sensor).
- The OT is arranged in a barrel made of two subsystems, TBPS for the innermost 3 layers and TB2S for the outermost 3 layers, and 5(x2) endcap discs (TEDD). The OT will cover a surface of about 192 m² for a total of 42M strip and 170M macro pixel channels. The PS modules are
- deployed in the first three layers of the Outer Tracker, in the radial region of 200 600 mm
- ²⁷ and in rings on disc-like structure in the endcaps up to radii 700 mm [3]. The 2S modules are
- deployed in the outermost three layers in Barrel (in the radial region above 600 mm) and in the large radii rings in the endcaps. The proposed layout of the Tracker is shown in Fig.1.



Figure 1: Sketch of one quarter of the layout of the CMS Tracker for HL-LHC in the r - z view. Inner Tracker 1x2 and 2x2 readout chips modules are shown in green and yellow respectively, Outer Tracker PS and 2S modules in blue and red.

³⁰ Pairs of closely spaced detector layers are inspected to see if they have pairs of clusters consis-

tent with the passage of a high momentum particle. For each hit in the inner layer (closer to the

³² interaction point), a window is opened on the outer layer. If a hit is found within the window,

³³ a stub is generated. Each stub consists of a position and a rough $p_{\rm T}$ measurement. Sketch of a

²⁹

p_T -module showing the concept of stub is shown in Fig. 2.



Figure 2: Sketch of a p_T -module showing the concept of stub selection.

To perform stub correlation in the 2S modules, the signals of the top and bottom sensor are 35 routed to the same CMS binary chip (CBC), which performs the correlation logic. This is pos-36 sible by folding the readout hybrids around a stiffener. In the PS modules, strip signals are 37 processed by the strip-sensor ASIC (SSA), and macro-pixel signals by the macro-pixel ASIC 38 (MPA). The strip data is routed from the SSA to the MPA via a folded hybrid, which then per-39 forms the cluster correlation. A detailed description of the front-end electronics can be found 40 in [3]. One 2S front-end hybrid carries eight CBCs reading out the strips of the top and bot-41 tom sensors at one sensor end, plus the Concentrator Integrated Circuit (CIC), which serves 42 as interface between all the CBCs of the hybrid and the readout link. The role of the CIC is 43 mainly to aggregate and serialize the data of the readout chips and to distribute clock, trigger, 44 and control signals to them. One PS front-end hybrid houses eight SSAs reading out the strip 45 sensor, and the same CIC as used for 2S hybrids. All the front-end chips implement binary 46

⁴⁷ readout. Images of the 2S and PS modules are shown in Figure 3.



Figure 3: The 2S module (left) and PS module (right) of the Outer Tracker.

The data flow is organized in two separate paths: L1 readout (DAQ) and Trigger (TRIG). Each 48 CBC generates high p_T stub data at bunch crossing (BX) rate. The CBCs exchange data with 49 their neighbors to identify clusters spanning across chip boundaries. At a data transfer rate of 50 320 Mb/s, each CBC chip sends 1 bit of DAQ and 5 bit of TRIG data to the concentrator every 51 3.125 ns. This bandwidth is compatible with transferring up to three trigger stubs from each 52 CBC every BX, and sending unsparsified readout data from each CBC pipeline up to an aver-53 age L1-accept rate of 750 kHz. The transfer scheme and data formats in PS module are very 54 similar to those used in the 2S module. The data transfer bandwidth is compatible with trans-55 ferring up to five trigger stubs from each MPA every 2 BX, and sending all sparsified readout 56 data from each MPA pipeline up to a 750 kHz L1-accept rate with negligible loss. CBCs/MPAs 57 send out stubs to the CIC. The CIC format them into data packets containing the trigger in-58 formation from eight BX and the raw data from events passing the Level 1 (L1) trigger, before 59 transmission to the Low-power Gigabit Transceiver (lpGBT). Due to the available CIC band-60 width, additional stubs are discarded, but stubs are sorted such as to keep those with lower 61

2. Samples

bending, presumably corresponding to tracks with higher $p_{\rm T}$. The format of the CIC trigger 62 block has been described in details in [4]. The CIC bandwidth can be adjusted to the module 63 local occupancy by configuring the data rate (5.12 Gb/s or 10.24 Gb/s raw data rate, also re-64 ferred to as 5G and 10G) and/or the forward error correction (FEC) level (FEC5 or FEC12, up 65 to five or twelve consecutive bits in error can be corrected). This tuneability is used to increase 66 bandwidth where expected data rates are very high, at the expense of increased power dissi-67 pation and decreased error correction level. In Figure 4, layers and rings with 5G or 10G are 68 shown. In the current simulation code (see L1Trigger/TrackTrigger/python/TTStub_cfi.py), 69 the following limits on number of transferred stubs are considered based on the mentioned 70 bandwidths. 71

- CBClimit = cms.uint32(3), CBC chip limit (in stubs/chip/BX)
- MPAlimit = cms.uint32(5), MPA chip limit (in stubs/chip/2BX)
- SS5GCIClimit = cms.uint32(16), 2S 5G chip limit (in stubs/CIC/8BX)
- PS5GCIClimit = cms.uint32(16), PS 5G chip limit (in stubs/CIC/8BX)
- PS10GCIClimit = cms.uint32(35), PS 10G chip limit (in stubs/CIC/8BX)
- ⁷⁷ If number of stubs are more than CBC/MPA/CIC transfer threshold in 1/2/8 BX, they will
- ⁷⁸ not transfer to the next step. The rate of stubs that are lost because of the bandwidth of
- ⁷⁹ CBC/MPA/CIC are called "CBC/MPA/CIC fail" in this note.



Figure 4: Modules with 5G and 10G data rate.

80 2 Samples

The samples used here have been produced by CMSSW 11_3_0 and are listed in table 1. The detector geometry considered is the D76 (=T21 tracker).

Table 1: List of simulated samples (see https://twiki.cern.ch/twiki/bin/view/CMS/L1TrackMC#RelVal_MC_samples).

sample	PU	pт	Ν	DAS name
tī	0	-	10k	/RelValTTbar_14TeV/CMSSW_11_3_0-113X_mcRun4_realistic_v7_2026D76noPU-v1
tī	200	-	9k	/RelValTTbar_14TeV/CMSSW_11_3_0_pre6-PU_113X_mcRun4_realistic_v6_2026D76PU200-v1
Single electron	0	2-100	100k	/RelValSingleEFlatPt2To100/CMSSW_11_3_0_pre6-113X_mcRun4_realistic_v6_2026D76noPU-v2
Single electron	0	1.5-8	100k	/RelValSingleElectronFlatPt1p5To8/CMSSW_11_3_0_pre6-113X_mcRun4_realistic_v6_2026D76noPU-v1
Single muon	0	2-100	100k	/RelValSingleMuFlatPt2To100/CMSSW_11_3_0_pre6-113X_mcRun4_realistic_v6_2026D76noPU-v1
Single muon	0	1.5-8	100k	/RelValSingleMuFlatPt1p5To8/CMSSW_11_3_0_pre6-113X_mcRun_realistic_v6_2026D76noPU-v1
Displaced muon	0	2-100	100k	/RelValDisplacedMuPt2To100Dxy100/CMSSW_11_3_0_pre6-113X_mcRun4_realistic_v6_2026D76noPU-v1
Displaced muon	0	1.5-8	100k	/RelValDisplacedMuPt1p5To8Dxy100/CMSSW_11_3_0_pre6-113X_mcRun4_realistic_v6_2026D76noPU-v1

3 Stub rates

The stub rate is an important parameter for both the front-end and back-end electronics. At the front-end it is important to check that the average stub rate per module is well within the readout capacity of the detector. At the back-end, the stub multiplicity per trigger tower will impact directly the performance of the L1 tracking system, and must therefore stay under control.

Each stub is built from two clusters. Clusters are categorized into "genuine", "combinatoric" 89 and "unknown" based on their matching condition to the tracking particles (TP). If cluster is 90 matched to only one tracking particle or a single TP has more than 99% of the total $p_{\rm T}$ of all TP 91 associated to the cluster, cluster is called genuine. If more than one TP are matched to the cluster 92 and non of them has more than 99% of the total $p_{\rm T}$ of all TP, cluster is called combinatoric. If 93 no TP is matched, cluster is called unknown. See https://twiki.cern.ch/twiki/bin/ 94 viewauth/CMS/SLHCTrackerTriggerSWTools for more details. Stubs that are made from 95 these three cluster types are called "genuine", "combinatoric" and "unknown" according to 96 the following criteria; 97

• If both clusters are unknown, the stub is unknown.

• If only one cluster is unknown, the stub is combinatoric.

- If both clusters are genuine, and are associated to the same (main) TP, the stub is genuine.
- If both clusters are genuine, but are associated to different (main) TP, the stub is combinatoric.
- If one cluster is combinatoric and the other is genuine/combinatoric, and they both share exactly one TP in common, then the stub is genuine. (The clusters can have other TP besides the shared one, as long as these are not shared). If instead the clusters share 0 or 2 TP in common, then the stub is combinatoric.

¹⁰⁸ In Figure 5, stub rates per BX (PBX) and stub rate per BX per module (PBXPmodule) are shown ¹⁰⁹ for all, genuine, combinatoric, and unknown stubs for tt events with 200 PU. In Figure 6, stub ¹¹⁰ rate per BX per module is shown as a function of module η , ρ and z. Two dimensional plots ¹¹¹ where each bin corresponds to a module is shown in Figures 7 and 8 for barrel layers and ¹¹² endcap disks respectively.

As was discussed in the previous section, stubs can be lost because of the limited bandwidth 113 of the CBC/MPA/CIC data transfer. In Figure 9-10, fractions of all stubs that are failed by the 114 CBC/MPA/CIC are shown. Less than 2×10^{-3} of stubs are failed by the MPAs/CBCs in the 115 first three layers of the TB and in all TE disks. In TB2S, up to 5% of stubs are failed by the 116 CBC which is too much. We have compared the fraction of failed stubs that are genuine to 117 the combinatoric and unknown stubs in Figure 11. Genuine stubs that are lost in the last three 118 layers are 1-1.5 % of total genuine stubs. In addition, most of these stubs are from low $p_{\rm T}$ TPs. 119 In figure 12, fractions of genuine stubs with $p_T > 2 \text{ GeV} (p_T \text{ of the matched TP})$ that are failed by 120 the CBC/MPA are compared to those for all and genuine stubs. It can be seen that for genuine 121 stubs with $p_{\rm T}$ >2 GeV, the fraction rates are around 0.2%. In addition, CIC fail rates are well 122 bellow 0.1% in all detector regions. Therefore, the designed CBC/MPA (CIC) bandwidth lead 123 up to 0.2% (0.1%) inefficiencies for high $p_{\rm T}$ genuine stubs. 124

It is worth mentioning that our simulation of the FE inefficiencies is not really accurate. We are summing hits from $t\bar{t}$ + 200PU over the bunch crossings, whereas we should have just pileup in the bunches previous to the ttbar event. For this high an occupancy, its probably not a big



Figure 5: Stub rates per BX and stub rates per BX per module in barrel (left) and endcap (right) are shown for all, genuine, combinatoric and unknown stubs for $t\bar{t}$ events with 200 PU.

¹²⁸ effect. But, it means these numbers are pessimistic.



Figure 6: Stub rates per BX per module in barrel (left) and endcap (right) are shown for all stubs as a function of module η , ρ and z using t \overline{t} events with 200 PU.



Figure 7: Two dimensional stub rates distributions in barrel layers. Each bin corresponds to a module in z, ϕ position.



5

4.5

4

3.5

3

2.5 2

1.5 1

0.5

0

5

4.5

4

3.5

-3 -2.5

> 2 1.5

1

0.5 0

Figure 8: Two dimensional stub rates distributions in endcap disks. Each bin corresponds to a module in r, ϕ position.



Figure 9: Fraction of stubs that are lost by the CBC/MPA in barrel (left) and endcap (right) are shown as a function of stub types, module η , ρ , and z using t \overline{t} events with 200 PU.



Figure 10: Fraction of stubs that are lost by the CIC in barrel (left) and endcap (right) are shown as a function of stub types, module η , ρ , and z using t \overline{t} events with 200 PU.



Figure 11: Fraction of stubs that are lost by the CBC/MPAs in barrel are shown for genuine, combinatoric and unknown stubs using $t\bar{t}$ events with 200 PU.



Figure 12: Fraction of stubs that are lost by the CBC/MPAs in barrel are shown for all stubs, genuine stubs and genuine stubs with TP $p_{\rm T} > 2$ GeV using t $\bar{\rm t}$ events with 200 PU.

129 4 Stub efficiency

Stub efficiency, defined as the ratio of the number of genuine clusters (matched to a track) in
 single track events that are used in a genuine stubs to the number of all genuine clusters.

Stub efficiency (1) = $\frac{\text{Number of genuine clusters used in genuine stubs}}{\text{Number of genuine clusters}}$ (1)

To measure stub efficiencies for electrons, muons, and displaced muons, we use single lepton samples with zero PU listed in table 1. We loop over TPs in lepton gun sample and find matched clusters for each TP. Then we check if the matched clusters are used in stub construction to find the numerator of the above equation.

In single lepton sample, it is enough to find at least one stub in each layer/Disk. Therefore, we define another stub efficiency;

Stub efficiency (2) =
$$\frac{\text{Number of genuine clusters if a genuine stub is found in a layer/disk}}{\text{Number of genuine clusters}}$$

(2)

¹³⁶ In Figure 13-14, stub reconstruction efficiencies for electron, muon and displaced muon are

shown as a function of the TP $p_{\rm T}$ for the first and second efficiency definition. By construction, the second efficiency is higher than the first efficiency. Similar efficiency plots are shown as a

function of the stub η , TP d_0 and TP d_0 in Figures 15-20,



Figure 13: Stub reconstruction efficiencies in barrel layers for electron, muon and displaced muon as a function of TP $p_{\rm T}$. Both efficiency definitions defined in the text are shown.



Figure 14: Stub reconstruction efficiencies in endcap disks for electron, muon and displaced muon as a function of TP $p_{\rm T}$. Both efficiency definitions defined in the text are shown.



Figure 15: Stub reconstruction efficiencies in barrel layers for electron, muon and displaced muon as a function of Stub Eta. Both efficiency definitions defined in the text are shown.



Figure 16: Stub reconstruction efficiencies in endcap disks for electron, muon and displaced muon as a function of Stub Eta. Both efficiency definitions defined in the text are shown.



Figure 17: Stub reconstruction efficiencies in barrel layers for electron, muon and displaced muon as a function of TP d_0 . Both efficiency definitions defined in the text are shown.



Figure 18: Stub reconstruction efficiencies in endcap disks for electron, muon and displaced muon as a function of TP d_0 . Both efficiency definitions defined in the text are shown.



Figure 19: Stub reconstruction efficiencies in barrel layers for electron, muon and displaced muon as a function of TP z_0 . Both efficiency definitions defined in the text are shown.



Figure 20: Stub reconstruction efficiencies in endcap disks for electron, muon and displaced muon as a function of TP z_0 . Both efficiency definitions defined in the text are shown.

5. Decoding Bend

140 5 Decoding Bend

The $p_{\rm T}$ of a track is estimated from the cluster displacement between the top and bottom sensor of a $p_{\rm T}$ module. This quantity, in units of detector strips, is known as the bend. The bend can be approximated from track parameters with

$$bend = \Delta r \frac{r}{2p} rinv = \Delta r \frac{1.14qr}{2p_{\rm T}}$$

Where r is the radial position of the hit, p is the strip pitch, rinv is the inverse radius of curvature of the track, q is the charge. Δr is the radial separation of the hits in a $p_{\rm T}$ module given by:

$$\Delta r = \frac{s}{\sin(\alpha)\frac{z}{r} + \cos(\alpha)}; \ \alpha_{flat} = 0^{\circ}, \ \alpha_{disk} = 90^{\circ}$$

ς

143

The bend, measured in half-strip bins, is encoded into 3 or 4 bits (PS/2S) which represent the range of bends accepted for that module. In general the bend bins are merged starting with high bend or low $p_{\rm T}$ bins. This loss of resolution only occurs for modules with stub window size larger than 1.5/3.5 (PS/2S). To use the encoded bend for a set of modules we define a map from encoded bend to some bend parameter, which is then used to estimate $p_{\rm T}$. This map is what we call the bend decoding.

The stub-to-stub or stub-to-track bend correlations are quickly assessed via the use of pre-150 computed lookup tables (LUT) that are indexed by stub positions and encoded bends. Hard-151 ware constraints limit the granularity of lookup table bins, in particular this means that any sin-152 gle r/z bin in the disks and PS layers may contain several modules for which the same encoded 153 bend represents different values of $p_{\rm T}$. The bend decoding must account for this variation for 154 optimal performance. The bend decoding for some region is constructed by considering all 155 modules and their bends which map to the encoded bend. Using this we can construct a range 156 in our bend parameter that covers the variation of all the modules in that LUT region. 157

In the legacy algorithm the bend decoding is defined using simulated events. This was esti-158 mated by optimizing the efficiency in single muon events and then adjusting the rate in some 159 areas with ttbar+200PU events. This method does not require knowledge of module tilt, win-160 dow sizes, or encoding scheme. The drawback is that in general any change to the bend win-161 dow sizes, encoding scheme, bend parameter, or LUT r/z bins requires the user to redefine the 162 bend decoding. Here we introduce a process for which the bend decoding can be calculated as 163 a function of the stub window sizes and LUT r/z bins. These changes can enable future studies 164 involving alternative bend parameters, LUT r/z bins, or encoding schemes. 165

In practice the bend is decoded in terms of a quantity called bendstrip which is proportional to the inverse radius of curvature (rinv) and is inversely proportional to $p_{\rm T}$. The bendstrip is calculated from track parameters using:

$$bendstrip = 0.18\frac{r}{2}rinv$$

Where 0.18 represents the sensor spacing for the 2S modules and r is the radial position of the stub. This bend parameter works well for the PS/2S layers due to a single layer varying only a little in r however this introduces issues when decoding the bend in the disks. The mean bendstrip for a particular encoded bend, depends on the radial position of the stub as shown in



Figure 21: Representation of the encoding and proposed decoding algorithm for three rings in layer 1. Each row shows the encoding of a specific ring and their lengths represent the range in bendstrip that is covered by their stub window size. The half integer numbers are the possible (positive) bends, and the colors represent their mapping to the encoded bend. The green dashed lines represent the decoded bend for an encoded bend of 2. The encoded bend is a representation of the detector bend in 3 bits, an encoded bend of 2 does not correspond to a detector bend of 2. The bend cut is a tunable parameter.



Figure 22: Representation of a potential rinv encoding/decoding algorithm for three rings in layer 1. Each row shows the encoding of a specific ring and their lengths represent the range in rinv that is covered by their stub window size. The half integer numbers are the possible (positive) bends, and the colors represent their mapping to the encoded rinv. The black dashed lines are the rinv bins, the green dashed lines represent the decoded rinv for an encoded rinv of 2.

figure 23. To account for this additional r bins were added to the lookup tables used during the
track seeding stage (TrackletEngine). It may be beneficial to also add additional r bins to the
lookup tables in the track-to-stub association stage (MatchEngine). A different choice of bend

parameter (rinv) or encoding scheme may also fix this issue.

This improvement to the bend decoding process is enabled in part by the use of module information obtained with the SensorModule class implemented in L1Trigger/TrackTrigger. Without the module information (position, tilt, stub window size) we would not be able to properly represent a modules bend in whatever bend parameter space we are using. To get this information where we need it we are required to pass the Setup class (L1Trigger/TrackTrigger) through to the TrackletLUT. In the TrackletLUT we define new methods which are used to decode the bend in LUT creation.

The bend decoding process uses the methods getSensorModules, getBendCut, and sometimes, getTanRange which are defined in the TrackletLUT class. To decode the bend we first find a set of all modules for which we want the decoding to be valid. This is done using the getSensor-Modules method. There are two ways that this method is used in the track trigger code. The

5. Decoding Bend



Figure 23: The dashed lines represent the mean bendstrip for an ensemble of stubs, with an encoded bend of 2, in a particular r-bin of disk 1 (PS). This shows that the bendstrip for a particular encoded bend varies as a function of r in the disks. To recover bend resolution one can either bin the disks in r or use a bend parameter which is independent of r. These stubs are taken from a sample of 5000 TTbar 200PU events.

- default is to return all modules, unique in |z| for a given layer/disk and module type (PS/2S); this is used mostly in the MatchEngine. For the TrackletEngine lookup tables we can reduce
- the number of modules by passing the getSensorModules method a range in $tan(\theta)$ that will
- ¹⁹¹ cover only the relevant modules. Theta here is measured with respect to the radial axis. To
- account for displaced tracks the max/min tan(θ) are measured from ±15 cm along the z axis.
- Once we find our sensor modules we pass that information to the getBendCut method. To 193 start we initialize a few data structures to store our bend decoding information and then loop 194 over all the sensor modules. For each module we loop over all possible bend values, which are 195 determined by the stub window size. For each bend in a given module we find its encoded 196 bend value and calculate the corresponding bend max/min, defined as the bend plus/minus 197 a bend cut. Finally we transform the bend max/min into the chosen bend parameter space, 198 bendstrip in this case, and update the bend decoding to cover this range for this particular 199 encoded bend value. This process provides a different bend decoding for every r/z bin in the 200 Tracklet/MatchEngine lookup tables. 201
- The bend cuts are used to balance the rates of real (true positive) and fake (false positive) stub 202 combinations or track projections, while keeping the total pass rate below the threshold set by 203 truncation. A real combination will pass in the LUT and also has matching tracking particles, 204 while a fake combination will pass in the LUT but not have any matching tracking particles. 205 Bend cuts which are too small will miss too many real tracks while bend cuts which are too 206 large will lead to real tracks being truncated. The tuning strategy used here is just to match the 207 true positive rate of the legacy algorithm. In general this method of decoding the bend results 208 in a lower false positive and therefore truncation rate while maintaining or improving the true 209 positive rate for the samples studied. 210
- ²¹¹ The bend cuts, defined in TrackFindingTracklet/Interface/Settings.h, are represented as multi-
- ²¹² ples of the approximate bend resolution:

$$\sigma_{bend} \approx \frac{1}{\sqrt{6}}[5]$$

²¹³ For the TrackletEngine the bend cuts are all between 2-2.6; the MatchEngine however requires

²¹⁴ bend cuts up to 4 to maintain efficiency because the disks are not binned in r. The true negative,

true positive, truncation, and false positive rates are compared in figure 24.



Figure 24: TrackletEngine (top) and MatchEngine (bottom) tuning. The Tracklet/MatchEngine associate stubs using their bend information. A "True" association is one in which all stubs share a matching tracking particle. A positive association is one that passes their respective LUT. The bend cuts are set such that the True Positive (Real) rate is larger than the legacy algorithm (equivalently a smaller True Negative rate). The bend cuts are parameterized by seed in the TrackletEngine and by layer/disk in the MatchEngine. These plots are made using 500 TTbar 200PU events.

216 6 Stub window tuning

Stubs are reconstructed by the CBC and MPA chips each time two correlated clusters will be found in the two layers (see Figure 2). Stub rates and reconstruction efficiencies depend on the stub acceptance window size. Establishing this window size, known as stub window (SW), in all the tracker regions is a fundamental step requiring a careful optimization. Indeed, small stub windows will ensure very good data reduction with a cost in efficiency, whereas large stub windows will provide good efficiency with a cost in rate [5].

As the signal information is binary, a group of adjacent hits is considered a cluster. The cluster width w is defined as the number of strips in the cluster

$$w = n_{last} - n_{first} + 1 \tag{3}$$

Where n_{first} and n_{last} are the indices of the first and last strips in the cluster, respectively, in accordance with the geometric order of the strips on the sensors. The cluster position X is defined as the mean value

$$X = \frac{n_{last} + n_{first}}{2} \tag{4}$$

²²³ The cluster width is given in steps of full-strips, while the position is in half-strips.

The stub position μ is defined as the mean cluster position per module

$$u = \frac{X_{top} + X_{bottom}}{2} \tag{5}$$

Where X_{top} and X_{bottom} are the cluster positions in the top and bottom sensor of the module, respectively. The stub window ΔX is defined as the difference between the cluster positions in the top and bottom sensor,

$$\Delta X = X_{top} - X_{bottom} \tag{6}$$

the stub window size is given in steps of half-strips, while the stub position is in quarter-strips. This window size varies from as little as two strips in the PS modules at the lowest radii in the forward region to nine strips in the current version of SW tune [5]. For the 2S modules the acceptance window varies between 6-15 strips. These acceptance windows are configurable and can be tuned to manage the rate for the trigger data [6].

The latest SW tune which is used in simulated samples are called "tight tune" which is optimized to ensure a good efficiency for muon stubs. There is another tune called "loose tune" in which electron efficiencies are also included (see https://indico.cern.ch/event/ 681577/contributions/2816628/attachments/1572998/2482715/UpgradeSim_111217. pdf). Stub windows should vary in different geometrical regions of the tracker to control rates and FE losses. In the current tune, SW is defined for 108 geometrical regions as are listed bellow and are shown in Figure 25;

- Flat modules in barrel layers (6 regions)
- Tilted modules in the first three layers $(3 \times 12 = 36 \text{ regions})$
- Rings in the first two disks ($2 \times 15 = 30$ regions)
- Rings in the last three disks $(3 \times 12 = 36 \text{ regions})$

In order to update the stub tune, we need to know the following variables in 108 geometrical
 regions of the tracker

• Stub rate as a function of stub window size

6. Stub window tuning



Figure 25: Tracker regions requiring a specific SW tuning. TB2S: Tracker Barrel with 2S modules. TBPS: Tracker Barrel with PS modules. TEDD: Tracker Endcap Double Disks [5].

• FE losses as a function of stub window size

• Stub efficiency for electron, muon as a function of stub window size

As was discussed in the previous sections, we use $t\bar{t}$ events with PU=200 for finding the stubrate/FE-losses and single lepton samples for measuring the stub reconstruction efficiencies. For SW tuning, we find efficiencies for muon in [2,8] GeV and electron in [4,8] GeV p_T range to be in the plateau of the efficiency turn on curve. We run the same chain of stub reconstruction using a fix value for the SW size in all 108 geometrical regions and measure the above variables. In the following, the input SW sizes for 108 geometrical regions of the tracker are printed for tight and loose tunes (see L1Trigger/TrackTrigger/python/TTStubAlgorithmRegister_cfi.py).

```
# PU200 tight tuning, optimized for muons
252
      BarrelCut = cms.vdouble( 0, 2, 2.5, 3.5, 4.5, 5.5, 7),
TiltedBarrelCutSet = cms.VPSet(
253
254
            255
                                                                                                      1, 1)),
256
257
                                                                                                         2.5)).
258
259
            ).
      EndcapCutSet = cms.VPSet(
260
            cms.PSet( EndcapCut = cms.vdouble( 0 ) ),
261
            cms.Pset(EndcapCut = cms.vdouble(0, 1, 2.5, 2.5, 3, 2.5, 3, 3.5, 4, 4, 4.5, 3.5, 4, 4.5, 5, 5.5)),
cms.Pset(EndcapCut = cms.vdouble(0, 0.5, 2.5, 2.5, 3, 2.5, 3, 3, 3.5, 3.5, 4, 3.5, 3.5, 4, 4.5, 5)),
cms.Pset(EndcapCut = cms.vdouble(0, 1, 3, 3, 2.5, 3.5, 3.5, 3.5, 4, 3.5, 3.5, 4, 4.5)),
cms.Pset(EndcapCut = cms.vdouble(0, 1, 2.5, 3, 2.5, 3.5, 3.5, 3.5, 3.5, 3.5, 3.5, 4, 4.5)),
262
263
264
265
            cms.PSet(EndcapCut = cms.vdouble(0, 0.5, 1.5, 3, 2.5, 3.5, 3,
266
                                                                                     3, 3.5,
                                                                                               4,
                                                                                                  3.5,
                                                                                                           3.5)),
267
          # PU200 loose tuning, optimized for robustness
268
         BarrelCut = cms.vdouble( 0, 2.0, 3, 4.5, 6, 6.5, 7.0),
TiltedBarrelCutSet = cms.VPSet(
269
270
               substitute(TiltedCut = cms.vdouble( 0 ) ),
cms.PSet( TiltedCut = cms.vdouble( 0 , 3, 3, 2.5, 3, 3, 2.5, 2.5, 2, 1.5, 1.5, 1, 1) ),
271
272
               273
274
275
              ).
276
277
         EndcapCutSet = cms.VPSet(
               278
279
280
281
282
283
```

We have calculated stub rates, FE losses, and stub efficiencies for the following fix SWs; 0.5, 1.0, 1.5, 2.0, 2.5, 3.0, 3.5, 4.0, 4.5, 5.0, 5.5, 6.0, 6.5, 7.0. For example,

```
#Fixed tune
286
          = cms.vdouble( 0, 1, 1, 1, 1, 1, 1),
287
    BarrelCut
   288
289
290
291
292
293
294
   EndcapCutSet = cms.VPSet(
      295
296
297
```

299 300 301	<pre>cms.PSet(EndcapCut = cms.vdouble(0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1)), cms.PSet(EndcapCut = cms.vdouble(0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1)),)</pre>
302	The following algorithm is used to choose the optimum window size with high-efficiency and
303	low-rate for each geometrical region:
304	• The CBC/MPA stub fail fraction should be less than 1%
305	• The CIC stub fail fraction should be less than 0.5%
306	Normalize the stub reconstruction efficiencies for electron and muon to the efficiency
307	obtained with the largest possible window size (7.0)
308	• The normalized stub reconstruction efficiencies for electron and muon should be
309	greater than 60%
310	• Choose the smallest window size where the efficiencies of the electron or muon do
311	not increase more than 0.005 with respect to the closest larger window size
312	The stub window tune which is optimized based on the stub reconstruction efficiency for muon
313	(muon + electron) is called "New tight" ("New loose"). New tunes are;
314 315 316	<pre># New tight tune based on simulated events CMSSW_11_3_0_pre3, D76 BarrelCut = cms.vdouble(0, 2.0, 2.0, 3.0, 4.5, 5.5, 6.5), TiltedBarrelCutSet = cms.VSet(</pre>

cms.PSet(EndcapCut = cms.vdouble(0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1)).

```
cms.PSet( TiltedCut = cms.vdouble( 0 ) ),
cms.PSet( TiltedCut = cms.vdouble( 0, 2.0, 2.0, 2.0, 2.5, 2.0, 2.0, 2.0, 1.5, 1.5, 1.5, 1.5, 1.0, 1.0) ),
cms.PSet( TiltedCut = cms.vdouble( 0, 2.5, 2.5, 2.5, 2.5, 2.0, 2.0, 2.0, 2.5, 2.5, 2.5, 2.0, 2.0, 2.0) ),
cms.PSet( TiltedCut = cms.vdouble(0, 3.5, 3.5, 3.0, 3.0, 3.0, 3.0, 2.5, 2.5, 2.5, 2.5, 2.5, 2.0) ))
317
318
319
320
321
322
                     EndcapCutSet = cms.VPSet(
                            Cms.PSet( EndcapCut = cms.vdouble(0 ) ),
cms.PSet( EndcapCut = cms.vdouble(0, 1.0, 1.5, 1.5, 2.0, 2.0, 2.5, 2.5, 3.0, 3.0, 4.0, 2.5, 3.0, 3.5, 4.0, 5.0) ),
cms.PSet( EndcapCut = cms.vdouble(0, 0.5, 1.5, 1.5, 2.0, 2.0, 2.0, 2.5, 2.5, 3.0, 3.5, 2.0, 2.5, 3.0, 4.0, 4.0) ),
cms.PSet( EndcapCut = cms.vdouble(0, 1.5, 2.0, 2.0, 2.0, 2.0, 2.5, 2.5, 3.5, 2.0, 2.5, 3.5) ),
cms.PSet( EndcapCut = cms.vdouble(0, 1.5, 1.5, 2.0, 2.0, 2.0, 2.0, 2.5, 2.5, 3.5, 2.0, 2.5, 3.5) ),
323
324
325
326
327
328
                             cms.PSet( EndcapCut = cms.vdouble(0, 1.0, 1.5, 1.5, 2.0, 2.0, 2.0, 2.0, 2.0, 2.5, 3.0, 2.0, 2.0,
                                                                                                                                                                                                                                     2.5))
329
330
331
           # New loose tune based on simulated events CMSSW_11_3_0_pre3,
332
                                                                                                                                                   D76
                    BarrelCut = cms.vdouble(0, 2.0, 3.0, 4.0, 5.0, 7.0, 7.0),
TiltedBarrelCutSet = cms.VPSet(
333
334
                             cms.PSet( TiltedCut = cms.vdouble( 0 ) ),
cms.PSet( TiltedCut = cms.vdouble( 0, 3.0, 2.0, 2.0, 3.0, 2.5, 3.0, 2.0, 1.5, 1.5, 1.5, 1.0, 1.0) ),
cms.PSet( TiltedCut = cms.vdouble( 0, 4.0, 3.5, 3.5, 3.5, 4.0, 4.0, 3.5, 5.0, 4.5, 4.0, 4.5, 3.0) ),
cms.PSet( TiltedCut = cms.vdouble( 0, 5.0, 5.0, 5.0, 4.0, 4.0, 4.0, 4.0, 4.0, 5.0, 6.0, 5.0, 5.5) ),
335
336
337
338
339
340
                     EndcapCutSet = cms.VPSet(
341
                            cms.PSet( EndcapCut = cms.vdouble(0)),
cms.PSet( EndcapCut = cms.vdouble(0, 1.0, 2.5, 5.0, 3.0, 4.5, 6.0, 6.0, 6.0, 6.0, 7.0, 6.0, 7.0, 6.0, 7.0, 7.0, 0),
cms.PSet( EndcapCut = cms.vdouble(0, 0.5, 2.5, 4.0, 5.0, 5.0, 4.0, 4.0, 6.0, 6.0, 7.0, 5.5, 6.0, 5.5, 6.5, 7.0)),
342
343
344
                             cms.PSet( EndcapCut = cms.vdouble(0, 3.5, 5.5, 6.5, 4.5, 6.0, 6.5, 7.0, 7.0, 4.5, 7.0, 7.0, 7.0) ),
cms.PSet( EndcapCut = cms.vdouble(0, 2.0, 5.5, 6.0, 6.0, 6.0, 6.0, 6.5, 6.0, 7.0, 7.0, 6.0, 7.0, 7.0) ),
345
346
                             cms.PSet( EndcapCut = cms.vdouble(0, 1.5, 4.5, 5.5, 5.0,
                                                                                                                                                          7.0,
                                                                                                                                                                     7.0,
                                                                                                                                                                                6.0,
                                                                                                                                                                                                                                        7.0) ),
347
348
349
```

In figures 26-36, rates, CBC/MPA fail fractions, CIC fail fractions, normalized muon and elec-350 tron efficiencies are shown in the barrel layers and endcap disks for above tunes. In figures 37-351 40, nominal stub reconstruction efficiencies (not normalized) for muon and electron are shown. 352 Each region of the mentioned 108 geometrical regions of the tracker are shown as an indepen-353 dent bin in x-axis. We have also divided the flat barrel part, although they are counted as one 354 region in stub tuning procedure. In the barrel histograms, first bin is related to the leftmost 355 module and last bin is related to the rightmost module in z-axis. In the endcap histograms, 356 first bin is related to the innermost ring and last bin is related to the outermost ring in r-axis. 357

In table 2, the total number of stubs are shown for the four available tunes. As it is clear from the last column of the table 2, the new tight tune leads to around 20% less stubs in the first

6. Stub window tuning

three layers in the barrel compared to the tight tune. Moreover, the stub rate reduction is more significant in the endcap disks (around 30% in all disks).

Barrel layer	Tight tune	loose Tune	New tight tune	New loose tune	new tight / tight
1	2.66e+03	2.66e+03	2.35e+03	2.55e+03	0.884
2	1.9e+03	2.62e+03	1.49e+03	2.72e+03	0.784
3	1.46e+03	2.16e+03	1.22e+03	1.91e+03	0.839
4	1.37e+03	1.78e+03	1.37e+03	1.51e+03	1.0
5	1.14e+03	1.31e+03	1.14e+03	1.39e+03	1.0
6	8.02e+02	8.02e+02	7.54e+02	8.01e+02	0.94
Endcap disks					
1	8.32e+02	1.18e+03	6.03e+02	1.19e+03	0.724
2	9.21e+02	1.38e+03	6.35e+02	1.4e+03	0.689
3	6.89e+02	1.19e+03	5.16e+02	1.36e+03	0.75
4	8.14e+02	1.42e+03	5.31e+02	1.64e+03	0.652
5	8.74e+02	1.51e+03	6.37e+02	1.89e+03	0.729

Table 2: Stub rate for the tight, loose, new tight, and new loose tunes



Figure 26: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in barrel layer 1.



Figure 27: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in barrel layer 2.



Figure 28: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in barrel layer 3.



Figure 29: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in barrel layer 4.



Figure 30: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in barrel layer 5.



Figure 31: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in barrel layer 6.



Figure 32: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in endcap disk 1.



Figure 33: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in endcap disk 2.



Figure 34: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in endcap disk 3.



Figure 35: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in endcap disk 4.



Figure 36: Distributions of stub rate (top left), CBC/MPA fail fraction (top right), CIC fail fraction (middle left), stub efficiency for electron (middle right), and stub efficiency for muon in endcap disk 5.



Figure 37: Distributions of stub efficiency for electron in Barrel layers.



Figure 38: Distributions of stub efficiency for electron in endcaps layers.



Figure 39: Distributions of stub efficiency for muon in Barrel layers.



Figure 40: Distributions of stub efficiency for muon in endcaps layers.

7 Validation of the new stub window tunes

As shown in table 2, the new tight tune leads to the lowest stub rates while keeping the fail rates small enough. So it could be used instead of the current tune. Before using the new tune, we need to check the effect of the new tunes on the L1 track reconstruction efficiencies. In addition, since we have not included the displaced muon stub efficiency in the stub window optimisation procedure, we need to make sure that the L1 track efficiency is not degraded for displaced tracks.

In order to measure the track reconstruction efficiencies for different stub window tunes we have used the nominal L1 tracking Ntuple maker ¹ with the following changes:

```
371 in the LlTrigger/TrackFindingTracklet/test/LlTrackNtupleMaker_cfg.py file
372 TP_minNStub = cms.int32(0), # require TP to have >= X number of stubs associated with it
373 TP_minNStubLayer = cms.int32(0), # require TP to have stubs in >= X Layers/disks
374 MCTruthClusterInputTag = cms.InputTag("TTClusterAssociatorFromPixelDigis", "ClusterInclusive")
```

In figures 41-43, track reconstruction efficiencies are shown for electron, muon, and ttbar general tracks. All four available tunes are shown for two cases, with or without the 'calcbendcut' (see section 5). In general, the old and new tunes show similar tracking efficiencies. Although the tight tune shows a bit higher efficiency (0.2%) compared to the new tight tune. It is worth mentioning that the 'calcbendfix' works since without the calcbend fix, the loose tunes have higher tracking efficiencies compared to the tight tunes.

In order to measure the L1 track reconstruction efficiency for displaced muon samples, we need
 to apply the following modifications in the L1 code;

383 in the L1Trigger/TrackFindingTracklet/test/L1TrackNtupleMaker_cfg.py file 384 L1TRKALGO = 'HYBRID_DISPLACED' 385 in the L1Trigger/TrackFindingTracklet/test/L1TrackNtuplePlot.C file 386 TP_minPt = 3.0, TP_maxEta = 2, TP_maxDxy = 10.0, TP_maxD0 = 10.0

In figure 45, track reconstruction efficiencies are shown for displaced muon tracks. All four 387 available tunes are shown for two cases, with or without the 'calcbendcut' (see section 5). The 388 new tight tune shows lower efficiency (\approx 8%) compared to the tight tune. In figure 45, track 389 reconstruction efficiencies are shown as a function of the track impact parameters (d_0 and z_0). 390 The observed inefficiencies are related to the tracks with large d_0 (> 3 cm). In order to find 391 the origin of the observed inefficiencies, we looked at the stub reconstruction efficiencies for 392 displaced muons (see section 4). The stub reconstruction efficiencies for all displaced muon 393 and displaced muon with $d_0 < 3$ cm are shown in figures 46 and 46 for barrel layers and 394 endcap disks. The most affected regions are barrel layers 2 and 3 the most inner rings in the 395 endcap disks. The L1 tracking efficiency for displaced muon as a function of η (see figure 44) 396 shows that the L1 tracking efficiency at high η are not highly affected. Therefore the L1 track 397 efficiencies for displaced muons are affected by tighter window sizes in barrel layers 2 and 3 in 398 the new tight tune compared to the tight tune. We found that by widening the stub window 399 sizes in barrel layers 2 and 3 of the new tight tune, we can restore the efficiency. Therefore, we 400 made a new tune called "Modified tight tune" as the following 401

```
402 # New modified tight tune based on simulated events CMSSW_11_3_0_pre3, D76
403 BarrelCut = cms.vdouble(0, 2.0, 2.5, 3.5, 4.0, 5.5, 6.5),
404 TiltedBarrelCutSet = cms.VPSet(
405 cms.PSet(TiltedCut = cms.vdouble(0)),
406 cms.PSet(TiltedCut = cms.vdouble(0, 2.0, 2.0, 2.0, 2.0, 2.0, 2.0, 1.5, 1.5, 1.5, 1.0, 1.0)),
407 cms.PSet(TiltedCut = cms.vdouble(0, 3.0, 3.0, 3.0, 3.0, 2.5, 2.5, 3.0, 3.0, 2.5, 2.5, 2.5)),
408 cms.PSet(TiltedCut = cms.vdouble(0, 4.0, 4.0, 4.0, 3.5, 3.5, 3.0, 3.0, 2.5, 2.5, 2.5, 2.5)),
409 ),
410 EndcapCutSet = cms.VPSet(
```

¹https://twiki.cern.ch/twiki/bin/view/CMS/L1TrackSoftware

411		cms.PSet(EndcapCut	=	cms.vdouble(0)),															
412		cms.PSet(EndcapCut	=	cms.vdouble(0,	1.0,	1.5,	1.5,	2.0,	2.0,	2.5,	2.5,	3.0,	4.0,	4.0,	2.5,	3.0,	3.5,	4.0,	5.0)),
413		cms.PSet(EndcapCut	=	cms.vdouble(0,	0.5,	1.5,	1.5,	2.0,	2.0,	2.0,	2.5,	2.5,	3.0,	3.5,	2.0,	2.5,	3.0,	4.0,	4.0)),
414		cms.PSet(EndcapCut	=	cms.vdouble(0,	1.5,	2.0,	2.0,	2.0,	2.0,	2.5,	3.0,	3.5,	2.5,	2.5,	3.0,	3.5)),			
415		cms.PSet(EndcapCut	=	cms.vdouble(0,	1.0,	1.5,	1.5,	2.0,	2.0,	2.0,	2.0,	3.0,	2.0,	2.0,	3.0,	3.0)),			
416		cms.PSet(EndcapCut	=	cms.vdouble(0,	1.0,	1.5,	1.5,	2.0,	2.0,	2.0,	2.0,	2.5,	3.0,	2.0,	2.0,	2.5)),			
417)																			
418	\																				

In figure 48, L1 track reconstruction efficiencies are shown as a function of the track parameter including the new modified tight tune. The efficiency loss at high d_0 are restored. So the new modified tight tune passes all validation tests.



Figure 41: L1 track reconstruction efficiency for electrons with four available tunes and the 'calcBendCut' variable true or false .



Figure 42: L1 track reconstruction efficiency for muons with four available tunes and the 'calcBendCut' variable true or false.



Figure 43: L1 track reconstruction efficiency for ttbar tracks with four available tunes and the 'calcBendCut' variable true or false.



Figure 44: L1 track reconstruction efficiency for displaced muons with four available tunes and the 'calcBendCut' variable true or false.



Figure 45: L1 track reconstruction efficiency for displaced muons as a function of the track impact parameters with four available tunes.



Figure 46: Stub reconstruction efficiencies in barrel layers for all displaced muon (top) and displaced muon with $|d_0| > 3$ cm (bottom) in barrel layers.



Figure 47: Stub reconstruction efficiencies in barrel layers for all displaced muon (top) and displaced muon with $|d_0| > 3$ cm (bottom) in endcap disks.



Figure 48: L1 track reconstruction efficiency for displaced muons as a function of the track impact parameters with four available tunes.

8. Summary

422 8 Summary

A new CMS Tracker is under development for operation at the High Luminosity LHC. It in-cludes an outer tracker based on dedicated modules that will reconstruct short track segments, called stubs, using spatially coincident clusters in two closely spaced silicon sensor layers. In this detector note, we studied various properties of the stubs using the latest simulated sam-ples. We have measured the stub rates, the fraction of stubs that are failed in data transmission and stub reconstruction efficiencies. These stub properties depend directly on the stub window size. We showed this dependency in various region of the tracker. We have developed an al-gorithm to combine these properties and extract optimum widow sizes in all detector regions. The final stub window tune that we propose to be used in the main L1 track trigger code is the following;

```
433
        # New modified tight tune based on simulated events CMSSW_11_3_0_pre3, D76
BarrelCut = cms.vdouble(0, 2.0, 2.5, 3.5, 4.0, 5.5, 6.5),
434
435
              TiltedBarrelCutSet = cms.VPSet(
                    cms.PSet( TiltedCut = cms.vdouble( 0 ) ),
cms.PSet( TiltedCut = cms.vdouble( 0, 2.0, 2.0, 2.0, 2.0, 2.0, 2.0, 2.0, 1.5, 1.5, 1.5, 1.5, 1.0, 1.0) ),
cms.PSet( TiltedCut = cms.vdouble( 0, 3.0, 3.0, 3.0, 3.0, 3.0, 2.5, 2.5, 3.0, 3.0, 2.5, 2.5, 2.5) ),
cms.PSet( TiltedCut = cms.vdouble(0, 4.0, 4.0, 4.0, 3.5, 3.5, 3.0, 3.0, 2.5, 2.5, 2.5, 2.5) ),
436
437
438
439
440
441
              EndcapCutSet = cms.VPSet(
                    442
443
444
445
446
447
448
449
```

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